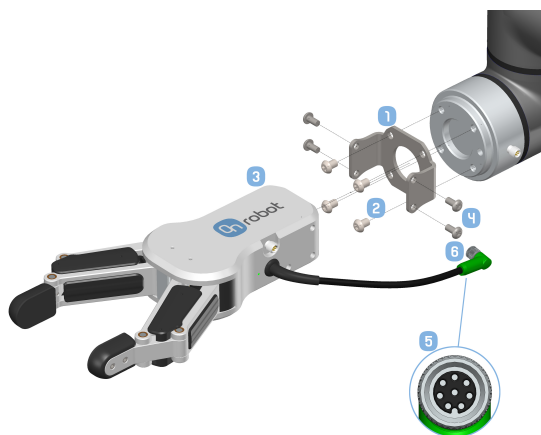




Quick Start

1 Mounting RG6



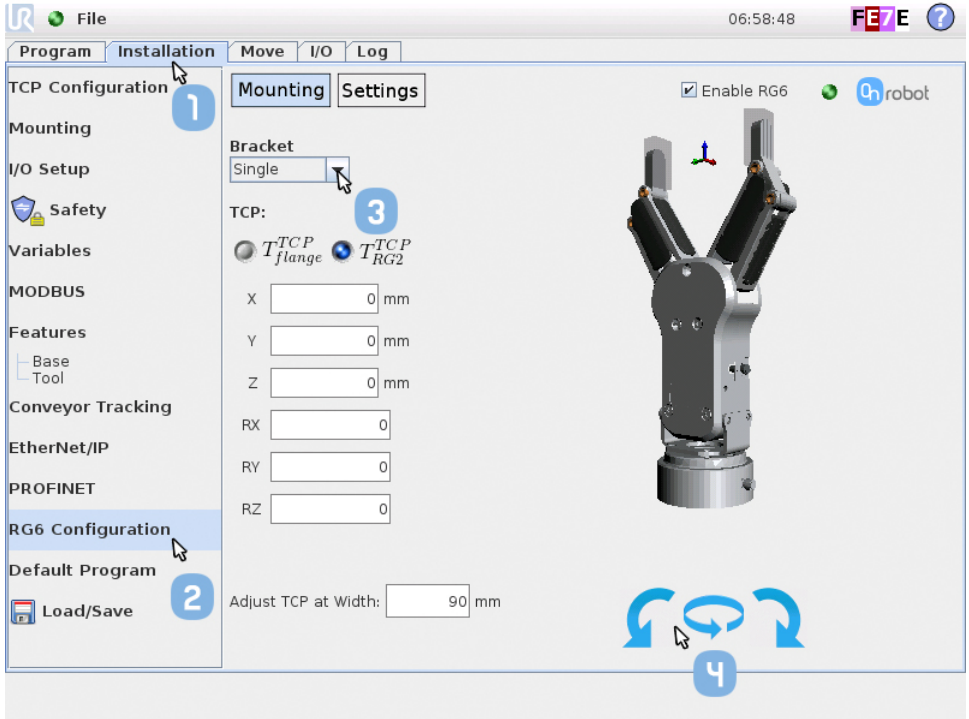
1. Place bracket in selected angle
2. Tighten M6 screws
3. Place RG6 in selected angle
4. Tighten M4 screws
5. Align the guide pin
6. Plug RG6 cable in robot

2 Insert USB



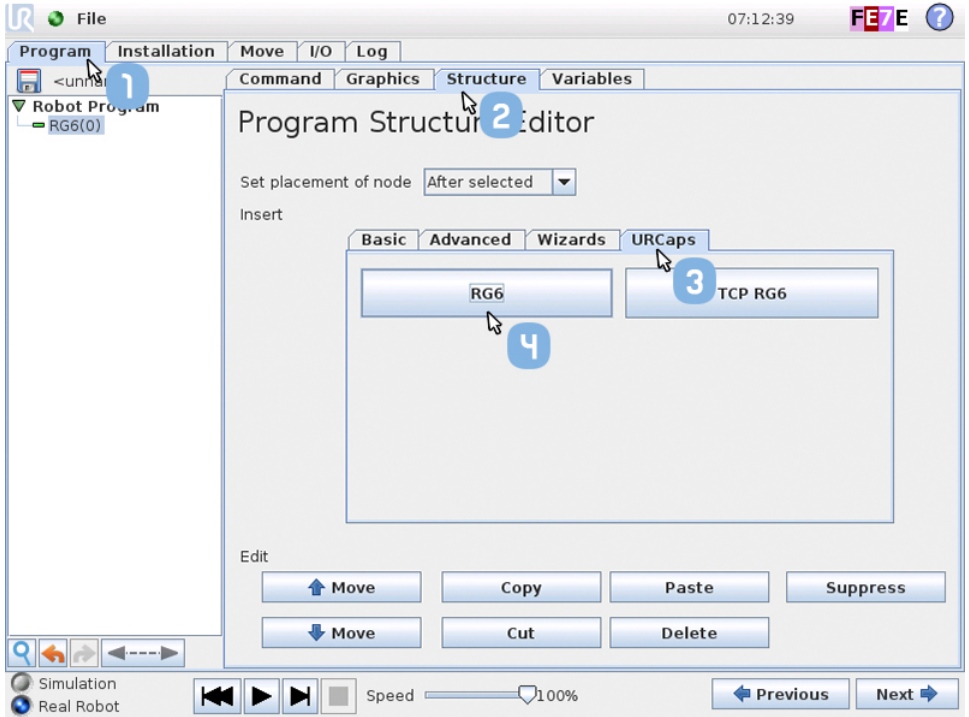
1. Power on system
2. Insert USB
3. Wait for system to reboot
4. Go to initialization screen
5. Press "ON", "START" and "OK"

3 Configure RG6 Mount



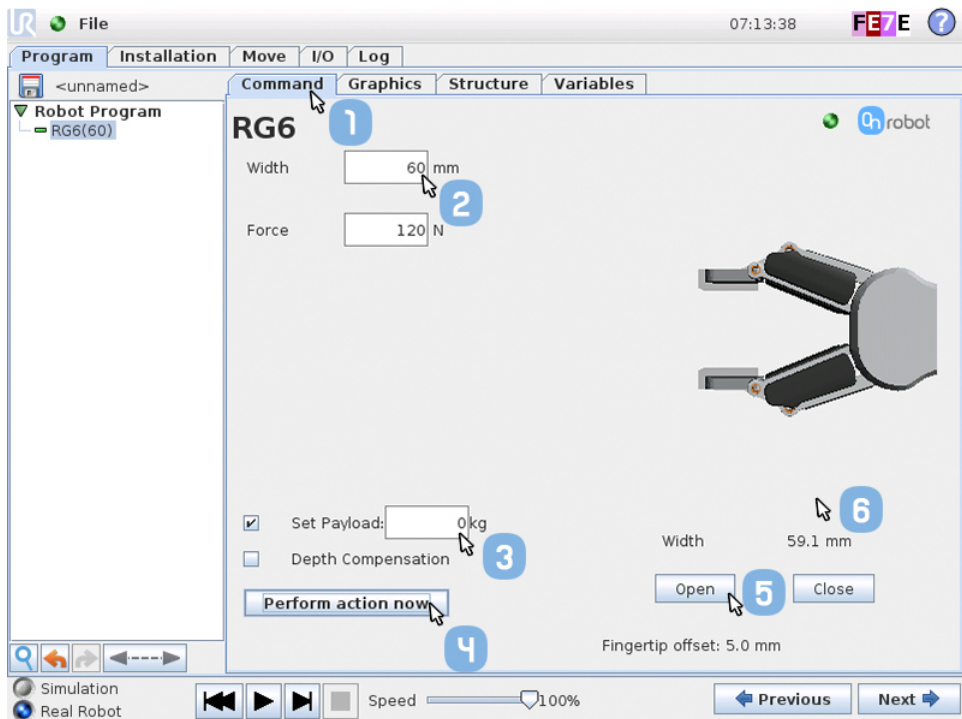
1. Go to **Installation** tap
2. Select **RG6 Configuration**
3. Select the **Bracket** type
4. Set the rotation of the bracket and the RG6

4 Add RG6 Node



1. Go to **Program** tap
2. Select **Structure**
3. Select **URCaps**
4. Press the **RG6** button

5 Configure RG6 Node



1. Go to **Command** tap
2. RG6 **Width** and **Force** can be adjusted
3. The **Payload** of RG6 can be set, and the total payload will automatically be calculated
4. **Perform action now** will make the RG6 do the selected action
5. Open and close the RG6 with the **Open & Close** buttons(hold-to-run)
6. Current RG6 feedback Width & Object detection can be read online on screen



WARNING: It is important that the user/implementer of this product have read and understood the manual before connecting the gripper to any equipment.