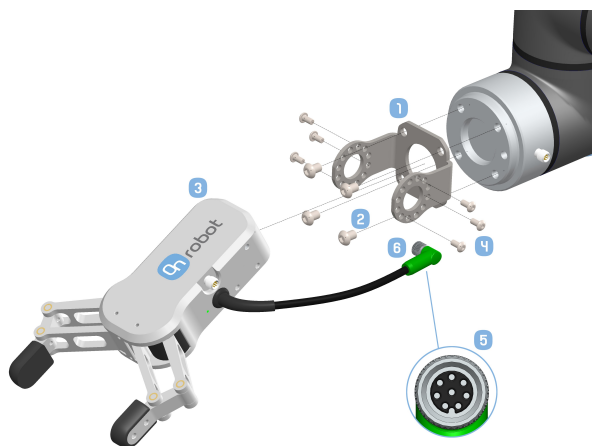




Quick Start

1 Mounting RG2



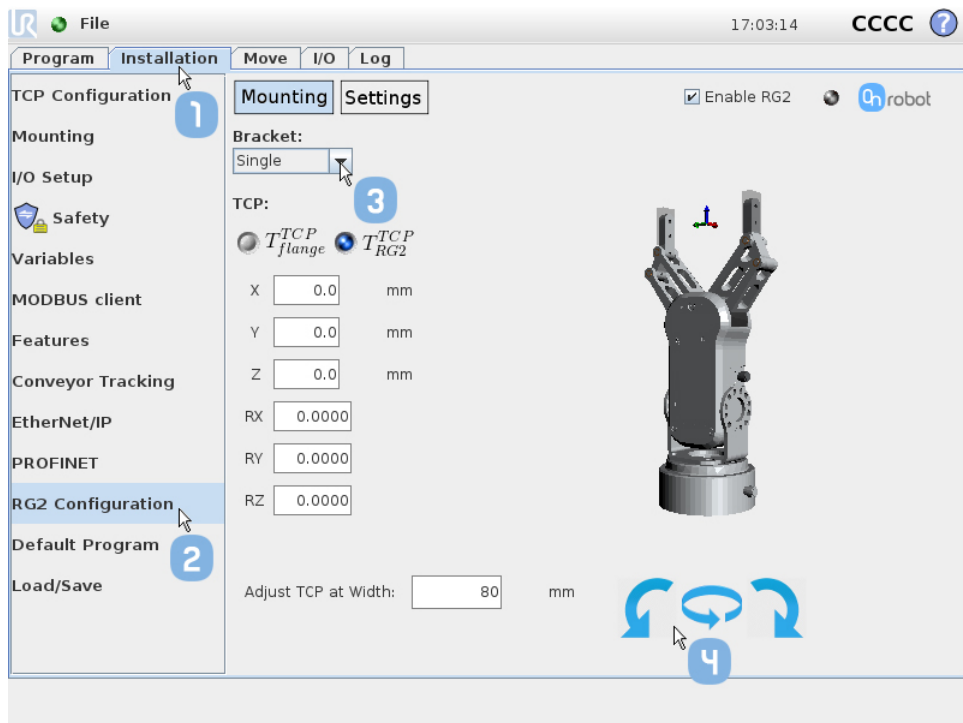
1. Place bracket in selected angle
2. Tighten M6 screws
3. Place RG2 in selected angle
4. Tighten M4 screws
5. Align the guide pin
6. Plug RG2 cable in robot

2 Insert USB



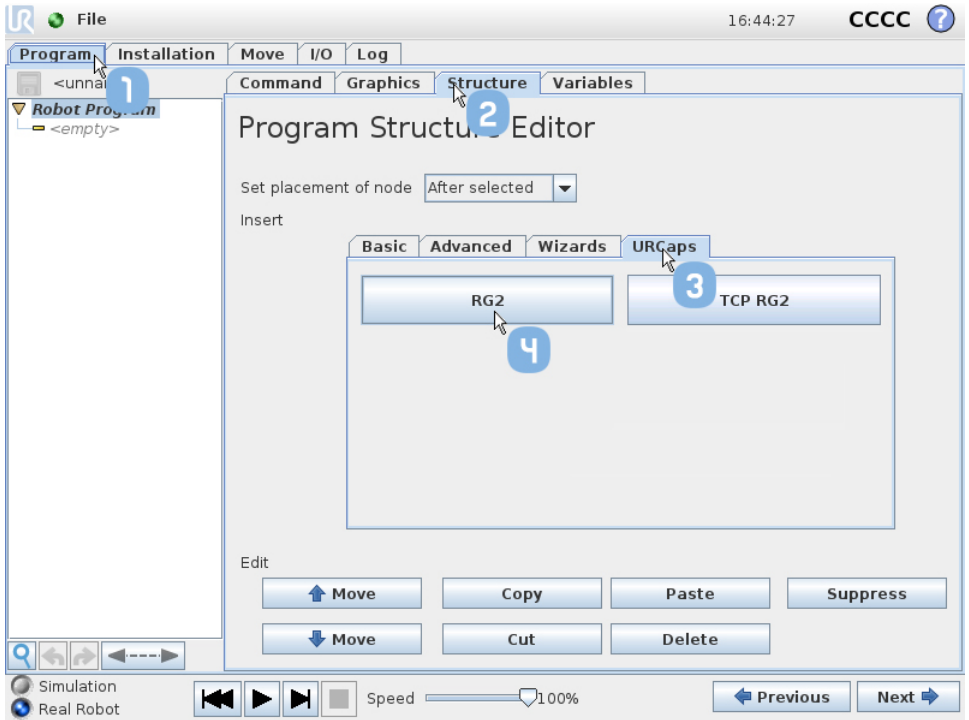
1. Power on system
2. Insert USB
3. Wait for system to reboot
4. Go to initialization screen
5. Press "ON", "START" and "OK"

3 Configure RG2 Mount



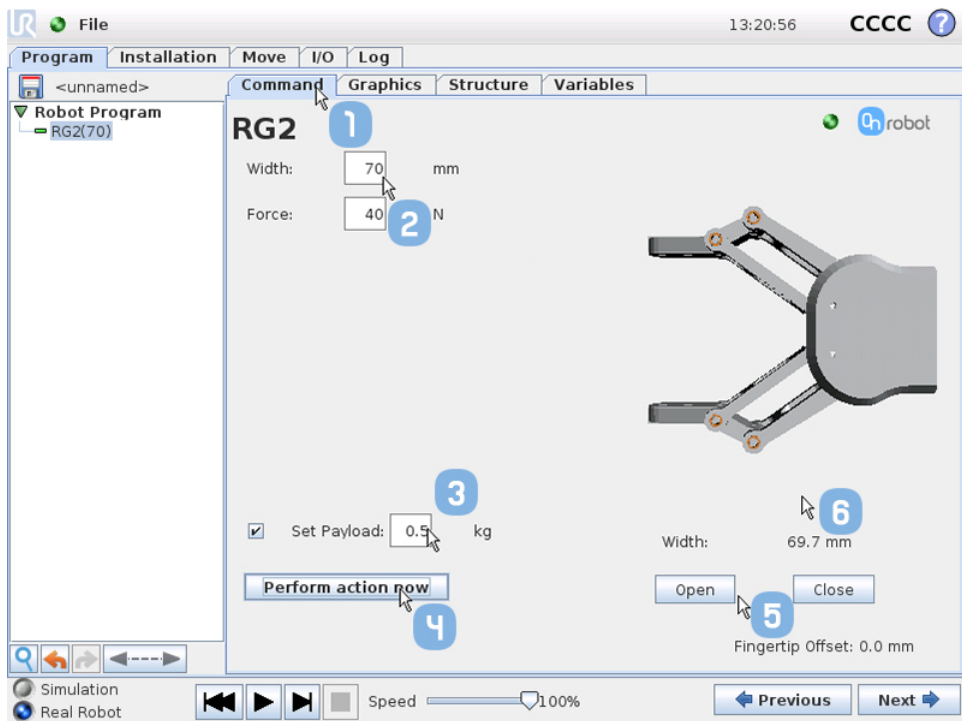
1. Go to **Installation** tap
2. Select **RG2 Configuration**
3. Select the **Bracket** type
4. Set the rotation of the bracket and the RG2

4 Add RG2 Node



1. Go to **Program** tap
2. Select **Structure**
3. Select **URCaps**
4. Press the **RG2** button

5 Configure RG2 Node



1. Go to **Command** tap
2. RG2 **Width** and **Force** can be adjusted
3. The **Payload** of RG2 can be set, and the total payload will automatically be calculated
4. **Perform action now** will make the RG2 do the selected action
5. Open and close the RG2 with the **Open & Close** buttons(hold-to-run)
6. Current RG2 feedback Width & Object detection can be read online on screen



WARNING: It is important that the user/implementer of this product have read and understood the manual before connecting the gripper to any equipment.