



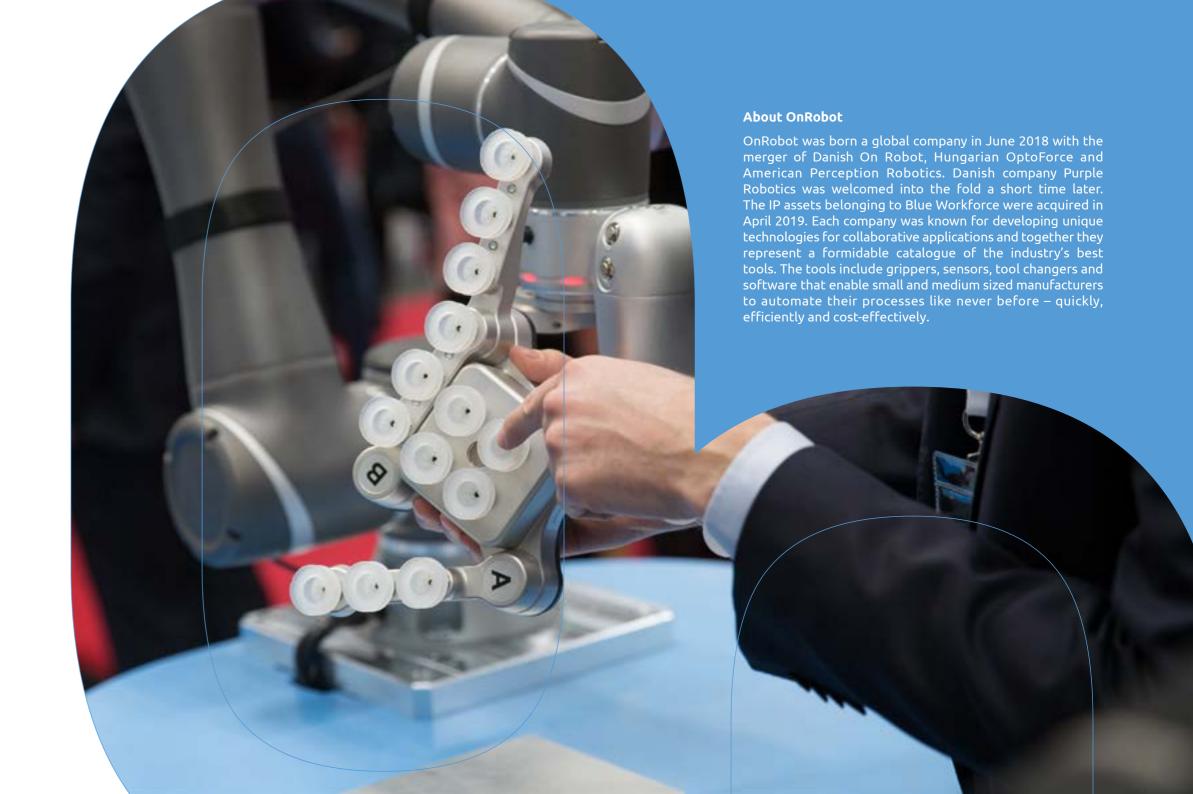


Collaborative applications are the future of automation, enabling rapid deployment, easy changeovers, and safe operation alongside human workers. Manufacturers gain true value from innovative collaborative applications that are enabled by a full range of Plug & Produce grippers, sensors, vision, and the software that drives them.

We offer the industry's broadest range of end-of-arm tooling and software solutions for collaborative applications, using a unified mechanical interface that helps manufacturers automate quickly and efficiently. Our innovative, manufacturer-focused approach saves you time and money so you can get on with the business of production.

We are excited to show you what you can accomplish with flexible, cost-effective collaborative applications.

Enrico Krog Iversen, CEO OnRobot





## Any robot you choose. One **OnRobot** system.

Save integration time and simplify deployment with our complete solution.







### **ANY APPLICATION**

## – What do you want to automate?

Now you can automate processes that were previously too complicated







Material Handling







Machine Tending



Quality

<sup>\*</sup>If your robot arm is not represented above, contact your local partner for information on compatibility on other robot brands.



## RG2/RG6

Plug & Produce grippers for multiple purposes

#### **RG2 TECHNICAL SPECIFICATIONS**

General Properties	Minimum	Maximum	Unit
Payload Force Fit	-	2 4.4	[kg] [lb]
Total stroke (adjustable)	0 0	110 4.33	[mm] [inch]
Gripping force (adjustable)	3	40	[N]
Gripping speed	38	127	[mm/s]
Gripping time	0.06	0.21	[s]
IP Classification	IP54		

#### **RG6 TECHNICAL SPECIFICATIONS**

General Properties	Minimum	Maximum	Unit
Payload Force Fit	-	6 13,2	[kg] [lb]
Total stroke (adjustable)	0	160 6.3	[mm] [inch]
Gripping force (adjustable)	25	120	[N]
Gripping speed	51	160	[mm/s]
Gripping time	0.05	0.15	S
IP Classification	54		

#### **POWER UP PRODUCTION**

- Flexible grippers can be used for a wide range of part sizes and shapes.
- Plug & Produce design reduces deployment time from a day to an hour.
- Easy deployment with out-of-the box grippers reduces programming time by 70%

## Applications:













### 3FG15 Flexible, large-stroke 3-finger gripper

#### TECHNICAL SPECIFICATIONS

General Pro	perties	Minimum Typical		Maximum	Unit
Payload Fo	Payload Force Fit		10/22		
Payload Fo	rm Fit	-	-	15 / 33	[kg] / [lb]
Grip Diameter*	External	4/0.16	-	152 / 5.98	[mm] / [inch]
Grip Diameter	Internal	35 / 1.38	-	181 / 7.12	[mm] / [inch]
Finger position	resolution	-	0.1 / 0.004	-	[mm] / [inch]
Repetition accuracy		-	0.1 / 0.004	0.2 / 0.007	[mm] / [inch]
Gripping f	Gripping force		10 - 240		
Gripping force (	adjustable)	3 - 100 [%]			[%]
Gripping s (diameter c		125 [mm/s]			[mm/s]
Gripping (including brake		- 500 - [ɪ			[ms]
Hold work if power l		Yes			
IP Classific	ation	IP67			
Dimensions [	L, W, Ø]	156 x 158 x 180 / 6.14 x 6.22 x 7.08 [mm] / [inch]			[mm] / [inch]
Weigh	t		1.15 / 2.5		[kg] / [lb]

#### **POWER UP PRODUCTION**

- Flexible production large-stroke **optimizes** CNC lathe-tending for multiple part sizes with a single 3-finger gripper
- Accurate centric positioning drives higher quality, consistency, and output with minimal programming
- Strong, stable grip and 3 contact points makes gripper fast and easy to redeploy for multiple processes
- Accomplish more with customizable fingertips to flexibly grip a wide range of part sizes and shapes

## **Applications:**









Can be used with products of various sizes and materials, including:















## Soft Gripper

### **Explore new automation** possibilities with certified food-grade soft gripper

#### **TECHNICAL SPECIFICATIONS**

General Properties	Minimum	Typical	Maximum	Unit	
Material	Two-component silicone rubber				
Food approval	FDA 2	FDA 21 CFR 177.2600 & EC/EU - 1935/2004			
Operation cycles		2.000.000		[cycles]	
Operation temperature	-20 / -4		80 / 176	[C] / [F]	
SG-tool attachment mechanism		Quick-lock	and Smart-loo	:k	
Weight Base Part		0.77 /1.69		[kg] / [lb]	
SG-a-H / SG-a-S					
Max payload	-	-	2.2 / 1.5 4.85 / 3.3	[kg] [lb]	
Work range, Grip dimensions (A)	11 / 0.43	-	75 / 2.95	[mm] / [inch]	
Work range, Grip depth (B)	-	38 / 1.496	-	[mm] / [inch]	
Soft part (SG-a-S) (C)	-	16 / 0.63	-	[mm] / [inch]	
Dimensions (HxØmax)	7	76x112 / 3 x 4	.4	[mm] / [inch]	
Weight (smart lock included)		0.168 / 0.37		[kg] / [lb]	
SG-b-H					
Max payload	-	-	1.1 / 2.42	[kg] / [lb]	
Work range, Grip dimensions (A)	24 / 0.94	-	118 / 4.65	[mm] / [inch]	
Work range, Grip depth (B)	-	40 / 1.57	-	[mm] / [inch]	
Dimensions (HxØmax)	77x109 / 3.03 x 4.29			[mm] / [inch]	
Weight (smart lock included)		0.172 / 0.379	)	[kg] / [lb]	

#### **POWER UP PRODUCTION**

- Explore new possibilities for food and beverage automation with certified food-grade soft gripper
- Easily handle a wide array of irregular shapes and delicate objects with flexible silicon-molded gripper
- Safely handle fragile and delicate objects for higher production quality and reduced waste
- No external air supply means no dust, no noise, no complexity, and no additional costs

## **Applications:**



# Soft Gripper



Can be used with products of various sizes and materials, including:



Organic material



















# OnRobot Eyes Adding vision to robotic applications has never been easier

#### TECHNICAL SPECIFICATIONS

Camera Characteristics				
Interface	USB-C 3.x			
Output Resolution	1280 x 1080			
Working distance	400-1000 mm			
Operating Temperature	0 – 35 °C			
IP rating	IP 54			
Eyes Features				
Type of vision system	2.5 D			
Minimum part size	10x10 mm or 15 mm diamet	ег		
Applications Supported	Detection, Sorting			
Mounting options supported	Robot and External			
	12 configurations (4 x 3)			
Reconfigurability when Robot mounted	Around robot's flange	Tilt orientations		
No see meeneed	0 - 90 - 180 - 270 (degrees)	0 - 45 - 90 (degrees)		
Detection processing time	Typ: 0.5 s			
Detection Repeatability	< 2 mm			
Detection Accuracy	External Mount	Robot Mount		
	Typ: 2 mm	Typ: 2 mm		
Application and set-up recommenda	ations			
Light conditions	No drastic, instant change			
Reflections and focused light spots	Keep minimal			
Characteristics of objects	Different from background	Different from background		
Camera with respect to workspace	Looking straight to it			

#### **POWER UP PRODUCTION**

- Quickly and easily add vision to robotic applications with one-picture calibration, fast programming and seamless gripper integration
- Affordable, efficient 2.5D vision offers depth perception for varying heights or stacked objects
- Flexible, adaptable vision system with on-robot or external mounting is ideal for almost any collaborative application
- Easily sort, pick and place unstructured applications with high reliability using any robot arm

## Applications:





ling Machine Tendii

















Robot wrist mount

External moun



### **OnRobot Screwdriver** Smart screwdriving solution for multiple processes

#### **TECHNICAL SPECIFICATIONS**

G	eneral Properties	Minimum	Typical	Maximum	Unit
	Screw size range	M1.6	-	M6	
	Torque range	0.15 / 0.11	-	5 / 3.68	[Nm] / [lbft]
Torque	If torque < 1.33Nm/0.98lbft	-	0.04 / 0.03	-	[Nm] / [lbft]
accuracy	If torque > 1.33Nm/0.98lbft	-	3	-	[%]
	Output speed	-	-	340	[RPM]
Screw	length within full safety	-	-	35 / 1.37	[mm] / [inch]
Shai	nk stroke (screw axis)	-	-	55 / 2.16	[mm] / [inch]
Shan	k preload (adjustable)	0	10	25	[N]
Sa	afety feature force	35	40	45	[N]
	Motor (x2)	Integrated,	electric BLDC		
	IP Classification	IP54			
Dimensions		308x86x114 12.1x3.4x4.		[mm] [inch]	
	Weight	2.5 / 5.51		[kg] / [lb]	
Sc	rew presenter sizes	M1.6; M2;	M2.5 ; M3 ; M4	; M5 ; M6	

#### **POWER UP PRODUCTION**

- Smart screwdriver easily automates multiple screwdriving processes with no downtime for manual changeovers
- Get the job done right—consistently and faster—with dynamic force control and intelligent error detection
- Expand your collaborative automation possibilities with built-in protective functions
- Get fast and easy deployment with automatic screw-feeding system and OnRobot's easy One System setup for any leading robot

## **Applications:**



## OnRobot Screwdriver





















### SP1/SP3/SP5 Gecko Single Pad Gripper

#### **TECHNICAL SPECIFICATIONS**

General Properties			Unit	
SP1		1 / 2.2	[kg] / [lb]	
Maximum payload	SP3	3 / 6.6	[kg] / [lb]	
	SP5	5/11	[kg] / [lb]	
	Minimum	SP1: 2.8 SP3: 8.2 SP5: 11.6	[N]	
Preload required	Medium	SP1: 8.2 SP3: 23.4 SP5: 33	[N]	
	Maximum	SP1: 13.3 SP3: 38.6 SP5: 54.4	[N]	
Detachment	time	100-1000 (dependent on robot speed)	[msec]	
Holds workpio power los		Yes. How long? Potentially days if well centered and undisturbed		
IP Classifica	tion	IP42		
Dimensions (	HxW)	69 x 71 / 2.7 x 2.8	[mm] / [inch]	
	SP1	0.267 / 0.587	[kg] / [lb]	
Weight	SP3	0.297 / 0.653	[kg] / [lb]	
SP5		0.318 / 0.7	[kg] / [lb]	

Pads general properties		Unit	
Material	Proprietary silicone blend		
Wear properties	Depends on surface roughness		
Change-out interval	~200.000	[cycles]	
Cleaning systems	OnRobot cleaning station     Silicone roller     Siporopyl Alcohol and lint-free cloth		
Cleaning interval	variable		
Recovery	100%		

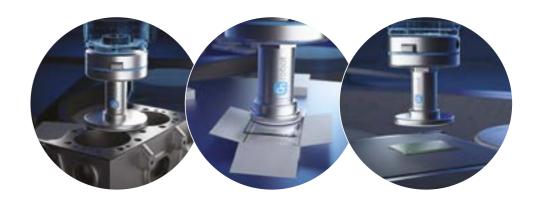
#### **POWER UP PRODUCTION**

- Compact, lightweight Gecko Single Pad Gripper requires no cables, electricity, air, or programming for cost-effective, plug-and-play performance
- Innovative adhesive gripper for flat, smooth, or perforated objects **automates** tasks that were previously not possible
- No-mark gripping even for shiny surfaces means no cleaning step is required, **saving** time and improving productivity
- No requirement for external air supply reduces noise and dust, lowers maintenance costs, and speeds deployment

## **Applications:**



# Gecko Single Pad Gripper









Can be used with products of various sizes and materials, including:



Plastic













## Pick & Collaborate helping hand with a sense of touch

The world's first gripper that can detect objects using built-in force/torque and proximity sensors.

#### **RG2-FT TECHNICAL SPECIFICATIONS**

<b>General Properties</b>	Minimum	Maximum	Unit
Payload Force Fit	-	2 4.4	[kg] [lb]
Total stroke (adjustable)	0	100 3.93	[mm] [inch]
IP Classification	IP54		

Force Sensor Properties	Fxy	Fz	Тху	Tz	Units
Nominal capacity (N.C.)	20	40	0.7	0.5	[N] [Nm]
Noise free resolu- tion	0.1	0.4	0.008	0.005	[N] [Nm]

#### **POWER UP PRODUCTION**

- Accurate sensing improves production quality by reducing defect rate as much as 60% in delicate Pick & Place processes.
- Easy-to-program sensing **allows robot** to act like an operator's third arm, with human-like part hand-offs.
- Ability to automate insertion tasks **that** weren't previously possible can reduce operation costs by 40%.

#### **Applications:**













Can be used with products of various sizes and materials, including:













## Grab & Go - flexible, adjustable electrical vacuum gripper

#### **VG10 TECHNICAL SPECIFICATIONS**

General Properties	Minimum	Maximum		Unit
Vacuum	5 % -0.05 1.5	80 % -0.810 24	-0.810	
Air flow	0	12		[Nl/min]
Payload	0 0	15 33		[kg] [lb]
Recommended workpiece size	10x10 0.5x0.5	500x500 20x20		
Vacuum cups	1	16		[pcs.]
Gripping time	-	0.35	-	[s]
Releasing time	-	0.20	-	[s]
Vacuum pump	Integrated, electric BL	DC		
Arms	4, adjustable by hand,	2 vacuum chanr	nels	
IP Classification	IP54			
Dimensions (folded)				n] :h]
Dimensions (unfolded)			[mr	
Weight	1.62 3.57		[kg] [lb]	l

#### **POWER UP PRODUCTION**

- Out-of-the-box deployment plug into the robot arm and configure the gripper to fit the product provides fast productivity and ROI.
- No external air supply required **reduces** maintenance costs and speeds deployment.
- Dual gripping functionality **enables shorter** cycle time.

## Applications:





Can be used with products of various















### VGC10 Compact vacuum gripper for all your needs

#### **VGC10 TECHNICAL SPECIFICATIONS**

General Properties	Minimum	Typical	Maximum	Unit
Vacuum	5 % -0.05 1.5	- - -	80 % -0.810 24	[Vacuum] [Bar] [inHg]
Air flow	0		12	[Nl/min]
Payload	0	-	15 33	[kg] [lb]
Recommended workpiece size	Unlimited, depends on custom arms			
Vacuum cups	1	-	7	[pcs.]
Gripping time	-	0.35	-	[s]
Releasing time	-	0.20	-	[s]
Vacuum pump	Integrated, e	lectric BLDC		
Arms	Replaceable,	customizable		
Dust filters	Integrated 50	)μm, field repla	ceable	
IP Classification	IP54			
Dimensions (folded)	101 x 100 x 100 [mm] 3.97 x 3.94 x 3.94 [inch]			
Weight	0.814 1.79			[kg] [lb]

#### **POWER UP PRODUCTION**

- Flexible electric vacuum gripper with unlimited customization fits all your application needs
- Small, lightweight gripper is perfect for tight spaces but with plenty of power for objects up to 15kg
- No external air supply needed for reduced maintenance costs and faster deployment

## Applications:













## VGC10

Can be used with products of various



















## Touch & Go – automation made simple with a sense of touch

#### **HEX-E QC TECHNICAL SPECIFICATIONS**

General Properties	6-Axis Force/Torque Sensor		Unit				
	Fxy	Fz	Txy	Tz			
Nominal Capacity (N.C)	200	200	10	5.5	[N] [Nm]		
Single axis deformation at N.C (typical)	± 1.7 ± 0.067	± 0.3 ± 0.011	± 2.5 ± 2.5	±5 ±5	[mm] [°] [inch] [°]		
Resolution ( Noise- free)	0.2	0.8	0.01	0.002	[N] [Nm]		
IP Classification	67						
Dimensions	50 x 71 x 93 1.97 x 2.79 x 3.0	[mm] [inch]					

#### **HEX-H QC TECHNICAL SPECIFICATIONS**

General Properties	6-Axis Force/Torque Sensor		Unit				
	Fxy	Fz	Txy	Tz			
Nominal Capacity (N.C)	200	200	20	13	[N] [Nm]		
Single axis deformation at N.C (typical)	± 0.6 ± 0.023	± 0.25 ± 0.009	± 2 ± 2	± 3.5 ± 3.5	[mm] [°] [inch] [°]		
Resolution ( Noise-free)	0.5	1	0.036	0.008	[N] [Nm]		
IP Classification	67						
Dimensions	50 x 71 x 93 1.97 x 2.79 x 3.66				[mm] [inch]		

#### **POWER UP PRODUCTION**

- Flexible sensor extends automation possibilities to processes that weren't previously possible.
- Out-of-the-box integration reduces deployment time for precise insertion tasks from months to days.
- High-accuracy sensor technology **provides 95%** better quality in insertion and assembly tasks.
- Sensor-based applications speed cycle time by up to 60% to produce more with the same number of employees.
- Easy programming gets even complex polishing tasks up and running in less than a day.

## **Applications:**



















## Quick Changer & Dual Quick Changer Bracket

With the Dual Quick Changer, you can now use two tools in one cycle, achieving higher utilization of your robots.



Quickly switch between tools to meet changing production needs.

# One Stop Shop for Collaborative Applications

All the tools you need at one place to automate more





### Find an OnRobot partner near you

We sell our products through a global network of valued partners - who have the tools, software, inspiration and training to develop any collaborative application their customers can imagine. Find a partner near you at

https://onrobot.com/en/partners.

**Business Card**