



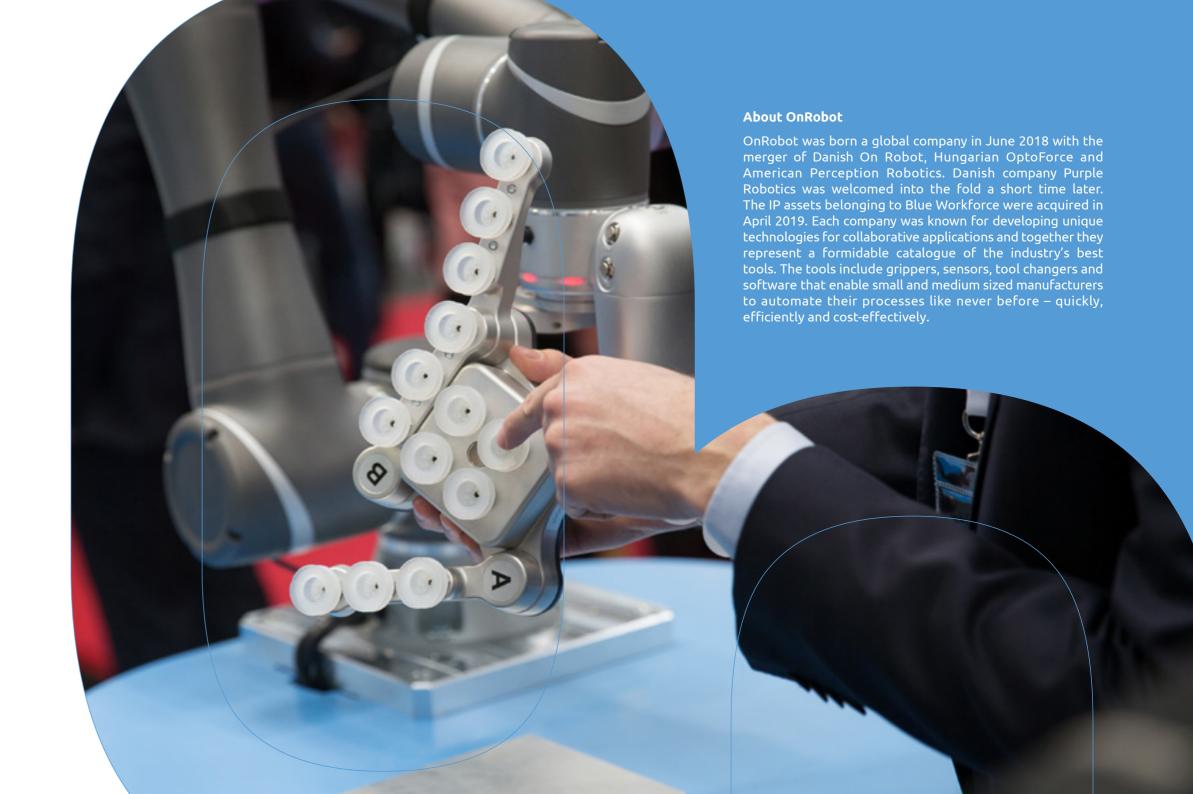


Collaborative applications are the future of automation, enabling rapid deployment, easy changeovers, and safe operation alongside human workers. Manufacturers gain true value from innovative collaborative applications that are enabled by a full range of Plug & Produce grippers, sensors, vision, and the software that drives them.

We offer the industry's broadest range of end-of-arm tooling and software solutions for collaborative applications, using a unified mechanical interface that helps manufacturers automate quickly and efficiently. Our innovative, manufacturer-focused approach saves you time and money so you can get on with the business of production.

We are excited to show you what you can accomplish with flexible, cost-effective collaborative applications.

Enrico Krog Iversen, CEO OnRobot





### Any robot you choose. One **OnRobot** system.

Save integration time and simplify deployment with our complete solution.







### **ANY APPLICATION**

## – What do you want to automate?

Now you can automate processes that were previously too complicated













Quality

<sup>\*</sup>If your robot arm is not represented above, contact your local partner for information on compatibility on other robot brands.



## RG2/RG6

Plug & Produce grippers for multiple purposes

#### **RG2 TECHNICAL SPECIFICATIONS**

General Properties	Minimum	Maximum	Unit
Payload Force Fit	-	2 4.4	[kg] [lb]
Total stroke (adjustable)	0	110 4.33	[mm] [inch]
Gripping force (adjustable)	3	40	[N]
Gripping speed	38	127	[mm/s]
Gripping time	0.06	0.21	[s]
IP Classification	IP54		

#### **RG6 TECHNICAL SPECIFICATIONS**

General Properties	Minimum	Maximum	Unit
Payload Force Fit	-	6 13,2	[kg] [lb]
Total stroke (adjustable)	0	160 6.3	[mm] [inch]
Gripping force (adjustable)	25	120	[N]
Gripping speed	51	160	[mm/s]
Gripping time	0.05	0.15	S
IP Classification	54		

### **POWER UP PRODUCTION**

- Flexible grippers can be used for a wide range of part sizes and shapes.
- Plug & Produce design reduces deployment time from a day to an hour.
- Easy deployment with out-of-the box grippers reduces programming time by 70%

## Applications:





















### 3FG15 Flexible, large-stroke 3-finger gripper

#### **TECHNICAL SPECIFICATIONS**

General Pro	General Properties		Minimum Typical Maximum		
Payload For	ce Fit	10/22			[kg] / [lb]
Payload Fo	rm Fit	-	-	15 / 33	[kg] / [lb]
Grip Diameter*	External	4/0.16	-	152 / 5.98	[mm] / [inch]
Grip Diameter*	Internal	35 / 1.38	-	181 / 7.12	[mm] / [inch]
Finger position	resolution	-	0.1 / 0.004	-	[mm] / [inch]
Repetition accuracy -			0.1 / 0.004	0.2 / 0.007	[mm] / [inch]
Gripping f	огсе	10	-	240	[N]
Gripping force (a	adjustable)	3	-	100	[%]
Gripping s (diameter cl		-	-	125	[mm/s]
Gripping t (including brake		-	- 500 -		
Hold work if power l		Yes			
IP Classific	ation	IP67			
Dimensions [	L, W, Ø]	156 x 158 x 180 / 6.14 x 6.22 x 7.08 [mm] / [inc			[mm] / [inch]
Weigh	t		1.15 / 2.5		[kg] / [lb]

### **POWER UP PRODUCTION**

- Flexible production large-stroke **optimizes** CNC lathe-tending for multiple part sizes with a single 3-finger gripper
- Accurate centric positioning drives **higher** quality, consistency, and output with minimal programming
- Strong, stable grip and 3 contact points makes gripper fast and easy to redeploy for multiple processes
- Accomplish more with customizable fingertips to flexibly grip a wide range of part sizes and shapes

### **Applications:**











### Soft Gripper

### **Explore new automation** possibilities with certified food-grade soft gripper

#### **TECHNICAL SPECIFICATIONS**

General Properties	Minimum	Typical	Maximum	Unit
Material	Т	wo-compone	nt silicone rul	bber
Food approval	FDA 21	1 CFR 177.260	00 & EC/EU - 1	935/2004
Operation cycles		2.000.000		[cycles]
Operation temperature	-20/-4		80 / 176	[C] / [F]
SG-tool attachment mechanism		Quick-lock	and Smart-loc	:k
Weight Base Part		0.77 /1.69		[kg] / [lb]
SG-a-H / SG-a-S				
Max payload	-	-	2.2 / 1.5 4.85 / 3.3	[kg] [lb]
Work range, Grip dimensions (A)	11 / 0.43	-	75 / 2.95	[mm] / [inch]
Work range, Grip depth (B)	-	38 / 1.496	-	[mm] / [inch]
Soft part (SG-a-S) (C)	-	16 / 0.63	-	[mm] / [inch]
Dimensions (HxØmax)	7	76x112 / 3 x 4	.4	[mm] / [inch]
Weight (smart lock included)		0.168 / 0.37		[kg] / [lb]
SG-b-H				
Max payload	-	-	1.1 / 2.42	[kg] / [lb]
Work range, Grip dimensions (A)	24 / 0.94	-	118 / 4.65	[mm] / [inch]
Work range, Grip depth (B)	-	40 / 1.57	-	[mm] / [inch]
Dimensions (HxØmax)	77:	x109 / 3.03 x	4.29	[mm] / [inch]
Weight (smart lock included)		0.172 / 0.379	)	[kg] / [lb]

#### **POWER UP PRODUCTION**

- Explore new possibilities for food and beverage automation with certified food-grade soft gripper
- Easily handle a wide array of irregular shapes and delicate objects with flexible silicon-molded gripper
- Safely handle fragile and delicate objects for higher production quality and reduced waste
- No external air supply means no dust, no noise, no complexity, and no additional costs

### **Applications:**



# Soft Gripper



Can be used with products of various sizes and materials, including:



Organic material

















### **OnRobot Eyes**

### Adding vision to robotic applications has never been easier

#### **TECHNICAL SPECIFICATIONS**

Camera Characteristics					Unit
Interface	USB-C 3.x				
Output Resolution	1280 x 720				[px]
Working distance	400-1000 [15.75 – 3	9.37]			mm [inch]
Operating Temperature	0 – 35 [32 – 95]				°C [°F]
IP rating	IP 54	IP 54			
Weight	0.260 [0.57]				kg [lb]
Eyes Features					Unit
Type of vision system	2.5 D				
Minimum part size	10x10 or 15 diameter [0.39x0.39 or 0.59 diameter]				mm [inch]
Applications Supported	Detection, Sorting, Inspection, Landmark				
Mounting options supported	Robot and External	Robot and External			
	12 configurations (4	l x 3)			
Reconfigurability when Robot mounted	Around robot's flan	ge	Tilt orientations		
	0 - 90 - 180 - 270		0 - 45 - 90		[degrees]
Detection Repeatability	< 2 [< 0.078]				mm [inch]
Detection Accuracy (typical)	External Mount		Robot Mount		
measured at 500 mm	2 [0.078]		2 [0.078]		mm [inch]
Minimum Inspection Defect Size	5 [0.197]				mm [inch]
	Waypoint distance from Landmark	Minimum error	Typical error	Maximum error	
Landmark accuracy **	200 [7.874]	0.2635 [0.0104]	0.6596 [0.0260]	0.9500 [0.0374]	mm [inch]
	500 [19.68]	0.6586 [0.0259]	1.6490 [0.0649]	2.3750 [0.0935]	mm [inch]
	1000 [39.37]	1.3173 [0.0519]	3.2981 [0.1298]	4.7500 [0.1870]	mm [inch]

#### **POWER UP PRODUCTION**

- Adding vision to robotic applications has never been easier, with one-picture calibration, fast programming and seamless gripper integration
- Flexible, adaptable vision system with on-robot or external mounting is ideal for almost any collaborative application
- Affordable, efficient 2.5D vision offers depth perception for varying heights or stacked objects
- Easily sort, pick and place unstructured applications with high reliability using any robot arm
- One-shot detection for multiple objects minimizes cycle time
- Inspect objects using color and contour detection with or without a robot, and ensure consistent quality
- Automatic landmark enables dynamic working environments and mobile robot setups

### Applications:

























Robot wrist mount



### **OnRobot Screwdriver** Smart screwdriving solution for multiple processes

#### **TECHNICAL SPECIFICATIONS**

G	eneral Properties	Minimum	Typical	Maximum	Unit
	Screw size range	M1.6	-	M6	
	Torque range	0.15 / 0.11	-	5 / 3.68	[Nm] / [lbft]
Torque	If torque < 1.33Nm/0.98lbft	-	0.04 / 0.03	-	[Nm] / [lbft]
accuracy	If torque > 1.33Nm/0.98lbft	-	3	-	[%]
	Output speed	-	-	340	[RPM]
Screw	length within full safety	-	-	35 / 1.37	[mm] / [inch]
Shai	nk stroke (screw axis)	-	-	55 / 2.16	[mm] / [inch]
Shan	k preload (adjustable)	0	10	25	[N]
Sa	afety feature force	35	40	45	[N]
	Motor (x2)	Integrated,	electric BLDC		
	IP Classification	IP54			
	Dimensions	308x86x114 12.1x3.4x4.5		[mm] [inch]	
	Weight	2.5 / 5.51		[kg] / [lb]	
Sc	rew presenter sizes	M1.6; M2;	M2.5 ; M3 ; M4	; M5 ; M6	

#### **POWER UP PRODUCTION**

- Smart screwdriver easily automates multiple screwdriving processes with no downtime for manual changeovers
- Get the job done right—consistently and faster—with dynamic force control and intelligent error detection
- Expand your collaborative automation possibilities with built-in protective functions
- Get fast and easy deployment with automatic screw-feeding system and OnRobot's easy One System setup for any leading robot

### **Applications:**



## OnRobot Screwdriver





















### OnRobot Sander

Complete surface finishing solution with fast and easy setup reduces complexity

#### **TECHNICAL SPECIFICATIONS**

General Properties		Minimum	Typical	Maximum	Unit	
Pad diamete	er	-	127 [5]			
Pad height		9.5 [0.37] mm [inc			mm [inch]	
Orbit size		-	-	5 [3/16]	mm [inch]	
Rotation spe	eed	1,000	-	10,000	RPM	
Ped type (31	M: 20353)		Clean San	ding Disc Pad		
Pad media t	уре		Но	okit™		
Pad weight		0.1 [0.22] kg [lb]			kg [lb]	
Weight		1.2 [2.645] kg [lb]			kg [lb]	
IP rating				P54		
Dimensions	(outer)		87 x 123 x 214 [3.42 x 4.84 x 8.42] mm		[inch]	
Operating (	Conditions	Minimum	Typical	Maximum	Unit	
Sanding pov	ver	-	150	-	W	
	External voltage	-	30	-	V	
Operation	External power	-	150	-	W	
voltage	Tool connector voltage	-	24	-	V	
	Tool connector power	-	2.4	-	W	
Operation to	emperature	0 [32]	-	50 [122]	°C [°F]	
Noise level a	at 10,000 RPM (3,000 RPM)	-	74 [44]	-	[dB]	

### **POWER UP PRODUCTION**

- Powerful and durable electric sander requires no compressed air, significantly reducing running and maintenance costs
- Cost-effective Grit Changer allows automatic switching between sanding grits without operator intervention for increased efficiency
- Flexible tool can be used on a wide range of part geometries and materials
- Sensing capabilities ensure precise adaptation to surface variations or part misalignment, improves product quality and consistency while reducing scrap
- Eliminates operator fatigue and hazards for easy compliance with local health and safety regulations

### Applications:



Sanding, Polishing, Buffing



## OnRobot Sander

Can be used with products of various sizes and materials, including:

















## SP1/SP3/SP5 Gecko Single Pad Gripper

#### **TECHNICAL SPECIFICATIONS**

General Properties			Unit		
	SP1	1 / 2.2	[kg] / [lb]		
Maximum payload	num payload SP3 3 / 6.6				
	SP5 5/11				
	Minimum	SP1: 2.8 SP3: 8.2 SP5: 11.6	[N]		
Preload required	Medium	SP1: 8.2 SP3: 23.4 SP5: 33	[N]		
	Maximum	SP1: 13.3 SP3: 38.6 SP5: 54.4	[N]		
Detachment	time	100-1000 (dependent on robot speed)	[msec]		
Holds workpie power los		Yes. How long? Potentially days if well centered and undisturbed			
IP Classification		IP42			
Dimensions (	HxW)	69 x 71 / 2.7 x 2.8	[mm] / [inch]		
_	SP1	0.267 / 0.587	[kg] / [lb]		
Weight	SP3	0.297 / 0.653	[kg] / [lb]		
	SP5	0.318 / 0.7	[kg] / [lb]		

Pads general properties		Unit	
Material	Proprietary silicone blend		
Wear properties	Depends on surface roughness		
Change-out interval	~200.000	[cycles]	
Cleaning systems	OnRobot cleaning station     Silicone roller     Silicone and lint-free cloth		
Cleaning interval	variable		
Recovery	100%		

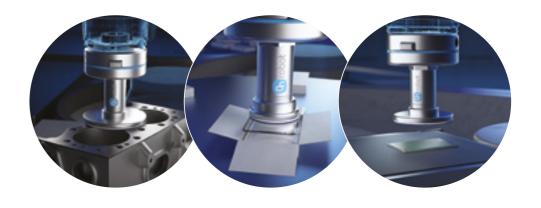
#### **POWER UP PRODUCTION**

- Compact, lightweight Gecko Single Pad Gripper requires no cables, electricity, air, or programming for cost-effective, plug-and-play performance
- Innovative adhesive gripper for flat, smooth, or perforated objects automates tasks that were previously not possible
- No-mark gripping even for shiny surfaces means no cleaning step is required, saving time and improving productivity
- No requirement for external air supply reduces noise and dust, lowers maintenance costs, and speeds deployment

### **Applications:**



# Gecko Single Pad Gripper







Can be used with products of various sizes and materials, including:



Plastic











Gl



### Pick & Collaborate helping hand with a sense of touch

The world's first gripper that can detect objects using built-in force/torque and proximity sensors.

#### **RG2-FT TECHNICAL SPECIFICATIONS**

<b>General Properties</b>	Minimum	Maximum	Unit
Payload Force Fit	-	2 4.4	[kg] [lb]
Total stroke (adjustable)	0 0	100 3.93	[mm] [inch]
IP Classification	IP54		

Force Sensor Properties	Fxy	Fz	Тху	Tz	Units
Nominal capacity (N.C.)	20	40	0.7	0.5	[N] [Nm]
Noise free resolu- tion	0.1	0.4	0.008	0.005	[N] [Nm]

### **POWER UP PRODUCTION**

- Accurate sensing improves production quality by reducing defect rate as much as 60% in delicate Pick & Place processes.
- Easy-to-program sensing allows robot to act like an operator's third arm, with human-like part hand-offs.
- Ability to automate insertion tasks **that** weren't previously possible can reduce operation costs by 40%.

### **Applications:**













Can be used with products of various sizes and materials, including:















## Grab & Go - flexible, adjustable electrical vacuum gripper

#### **VG10 TECHNICAL SPECIFICATIONS**

General Properties	Minimum	Maximum		Unit	
Vacuum	5 % -0.05 1.5	80 % -0.810 24	-0.810		
Air flow	0	12		[Nl/min]	
Payload	0	15 33		[kg] [lb]	
Recommended workpiece size	10x10 0.5x0.5	500x500 20x20			
Vacuum cups	1	16		[pcs.]	
Gripping time	-	0.35	-	[s]	
Releasing time	-	0.20	-	[s]	
Vacuum pump	Integrated, electric BL	DC			
Arms	4, adjustable by hand, i	2 vacuum chanr	iels		
IP Classification	IP54				
Dimensions (folded)				n] :h]	
Dimensions (unfolded)	1			n] :h]	
Weight	1.62 3.57		[kg] [lb]	l	

### **POWER UP PRODUCTION**

- Out-of-the-box deployment plug into the robot arm and configure the gripper to fit the product provides fast productivity and ROI.
- No external air supply required **reduces** maintenance costs and speeds deployment.
- Dual gripping functionality **enables shorter** cycle time.

### Applications:





Can be used with products of various















### VGC10 Compact vacuum gripper for all your needs

#### **VGC10 TECHNICAL SPECIFICATIONS**

General Properties	Minimum	Typical Maximum		Unit	
Vacuum	5 % -0.05 1.5	- - -	80 % -0.810 24	[Vacuum] [Bar] [inHg]	
Air flow	0		12	[Nl/min]	
Payload	0	-	15 33	[kg] [lb]	
Recommended workpiece size	Unlimited, depends on custom arms				
Vacuum cups	1	-	7	[pcs.]	
Gripping time	-	0.35	-	[s]	
Releasing time	-	0.20	-	[s]	
Vacuum pump	Integrated, electric BLDC				
Arms	Replaceable, customizable				
Dust filters	Integrated 50µm, field replaceable				
IP Classification	IP54				
Dimensions (folded)	101 x 100 x 100 3.97 x 3.94 x 3.94			[mm] [inch]	
Weight	0.814 1.79			[kg] [lb]	

### **POWER UP PRODUCTION**

- Flexible electric vacuum gripper with unlimited customization fits all your application needs
- Small, lightweight gripper is perfect for tight spaces but with plenty of power for objects up to 15kg
- No external air supply needed for reduced maintenance costs and faster deployment

### Applications:











# VGC10

Can be used with products of various



Plastic















## Touch & Go – automation made simple with a sense of touch

#### **HEX-E QC TECHNICAL SPECIFICATIONS**

General Properties	6-Axis Force/Torque Sensor		Unit			
	Fxy	Fz	Txy	Tz		
Nominal Capacity (N.C)	200	200	10	5.5	[N] [Nm]	
Single axis deformation at N.C (typical)	± 1.7 ± 0.067	± 0.3 ± 0.011	± 2.5 ± 2.5	± 5 ± 5	[mm] [°] [inch] [°]	
Resolution ( Noise- free)	0.2	0.8	0.01	0.002	[N] [Nm]	
IP Classification	67					
Dimensions	50 x 71 x 93 1.97 x 2.79 x 3.66				[mm] [inch]	

#### **HEX-H QC TECHNICAL SPECIFICATIONS**

General Properties	6-Axis Force/Torque Sensor		Unit			
	Fxy	Fz	Txy	Tz		
Nominal Capacity (N.C)	200	200	20	13	[N] [Nm]	
Single axis deformation at N.C (typical)	± 0.6 ± 0.023	± 0.25 ± 0.009	± 2 ± 2	± 3.5 ± 3.5	[mm] [°] [inch] [°]	
Resolution ( Noise-free)	0.5	1	0.036	0.008	[N] [Nm]	
IP Classification	67					
Dimensions	50 x 71 x 93 1.97 x 2.79 x 3.66				[mm] [inch]	

#### **POWER UP PRODUCTION**

- Flexible sensor extends automation possibilities to processes that weren't previously possible.
- Out-of-the-box integration reduces deployment time for precise insertion tasks from months to days.
- High-accuracy sensor technology **provides 95%** better quality in insertion and assembly tasks.
- Sensor-based applications speed cycle time by up to 60% to produce more with the same number of employees.
- Easy programming gets even complex polishing tasks up and running in less than a day.

### **Applications:**

























### Find an OnRobot partner near you

We sell our products through a global network of valued partners - who have the tools, software, inspiration and training to develop any collaborative application their customers can imagine. Find a partner near you at

https://onrobot.com/en/partners.

**Business Card**